

Thin Dual Lock Chuck DLR08





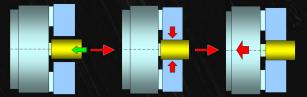
Moment of inertia reduced by 30% (compared to DL208)

High gripping accuracy Ideal for automation and thin workpiece machining

Dedicated for outer diameter gripping

2-step gripping of parallel movement and pull-down

Preventing work lift-up and seat confirmation applicable Wide gripping range up to the chuck outer diameter



Light weight and low inertia

Shortening the acceleration/deceleration time for reducing the cycle time and saving energy Thin body provides wide machining area

Gripping accuracy 0.01mm T.I.R. or less

High-precision gripping improves machining capability and is ideal for mass production

Ideal for machining easily distorted workpieces

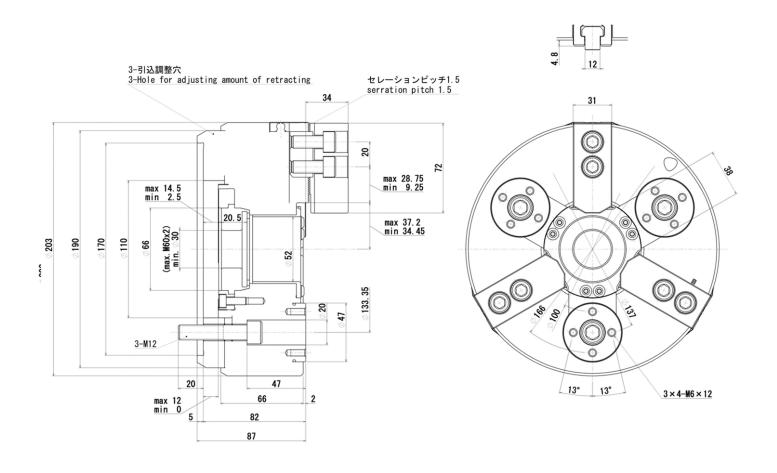
The pull-down amount can be adjusted while attached to the lathe spindle.

Optional T-Nut Plus can be used

Significant reduction in setup time by eliminating the re-forming after detaching and attaching jaws



Dimensions



Specifications

Model	Through hole mm	Grippin max. mm	g range min. mm	Jaw stroke (in dia.) mm	Plunger stroke mm		Max. draw bar pull force kN	5 5	Gripping force at max. speed kN	Mass	Moment of inertia kg·m²	Matching cylinder	Max. hyd. Pressure MPa	Standard soft jaws
DLR08	52	203	19	5.5	12	5000	24	60	20	17.2	0.095	S1552	1.86	SJ06B1
												SS1452K	1.98	
												SR1453C	2.41	

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