

INSTRUCTION MANUAL

PLS type

Work Gripper



DANGER

- This instruction manual is for production engineers and maintenance personnel in charge of operation of this product. When a beginner uses this product, receive instructions from experienced personnel, the distributor or our company.
- Before installing, operating or maintaining this equipment, carefully read this manual and the safety labels attached to the equipment. Failure to follow these instructions and safety precautions could result in serious injury, death, or property damage.
- Store this manual near equipment for future reference.
- If any questions related to safety arise about this manual, please confirm them with the distributor or our company.

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Preface

This manual provides detailed information about how to safely and correctly use the work gripper (PLS type).

Before starting to use this work gripper, read this manual carefully and always follow the instructions and warnings in "Important Safety Precautions" and "Precautions for Use" at beginning of the manual. Failure to follow these precautions could result in a serious accident.

Terms and Symbols Used for Safety Messages

In this manual, precautions for handling that are considered especially important are classified and displayed as shown below depending on the damage of risk including the seriousness of the harm that could result. Please sufficiently understand the meanings of these terms and follow the instructions for safe operation.

Safety Alert Symbol

The triangle is the safety alert symbol used to alert you to potential safety hazards that could result in injury or death.



Indicates a hazardous situation which, if you not avoided, will result in death or serious injury.



Indicates a hazardous situation which, if you not avoided, could result in death or serious injury.



Indicates a hazardous situation which, if you not avoided, could result in minor or moderate injury.



Indicates instructions which, if not avoided, could result in damage to the equipment or a shortened work life.

Liability and How to Use this Manual

This product is suitable for gripping a workpiece on the rotary tables or machining centers. This product is equipped with the jaws to clamp the workpiece and they operate by means of a built-in cylinder. For any other applications, please contact us.

Our company will not assume responsibility for injury, death, damage, or loss resulting from not following the instructions in this manual.

There are countless things that cannot or should not be done, and it is impossible to cover all of them in this manual.


Therefore, do not perform any actions unless they are specifically allowed in this manual. If any questions related to safety arise about operation, control, inspection and maintenance which are not specified in this manual, please confirm them with our company or distributor before performing them.

Guarantee and Limitation of Liability

The guarantee period of this product is 1 year after delivery.

Use the parts delivered by **Kitagawa Corporation** for all the parts including consumable parts. We will not assume responsibility for injury, death, damage, or loss caused by usage of parts not manufactured by **Kitagawa Corporation**. Additionally, if parts other than genuine parts manufactured by **Kitagawa Corporation** are used, this guarantee will be completely invalid.

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1. Structural Drawing and Parts List

1-1. Type display

Type display as shown below

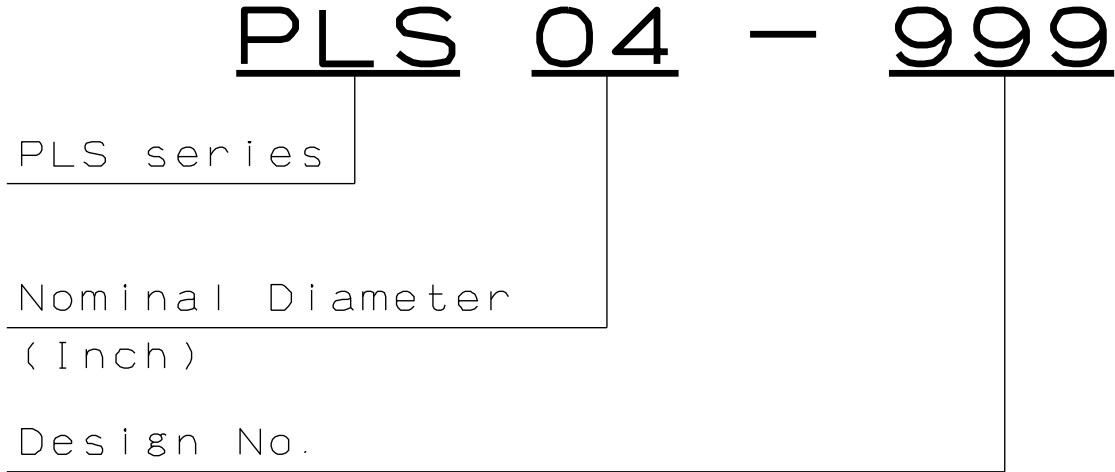


Fig.1

1-2. Structural drawing

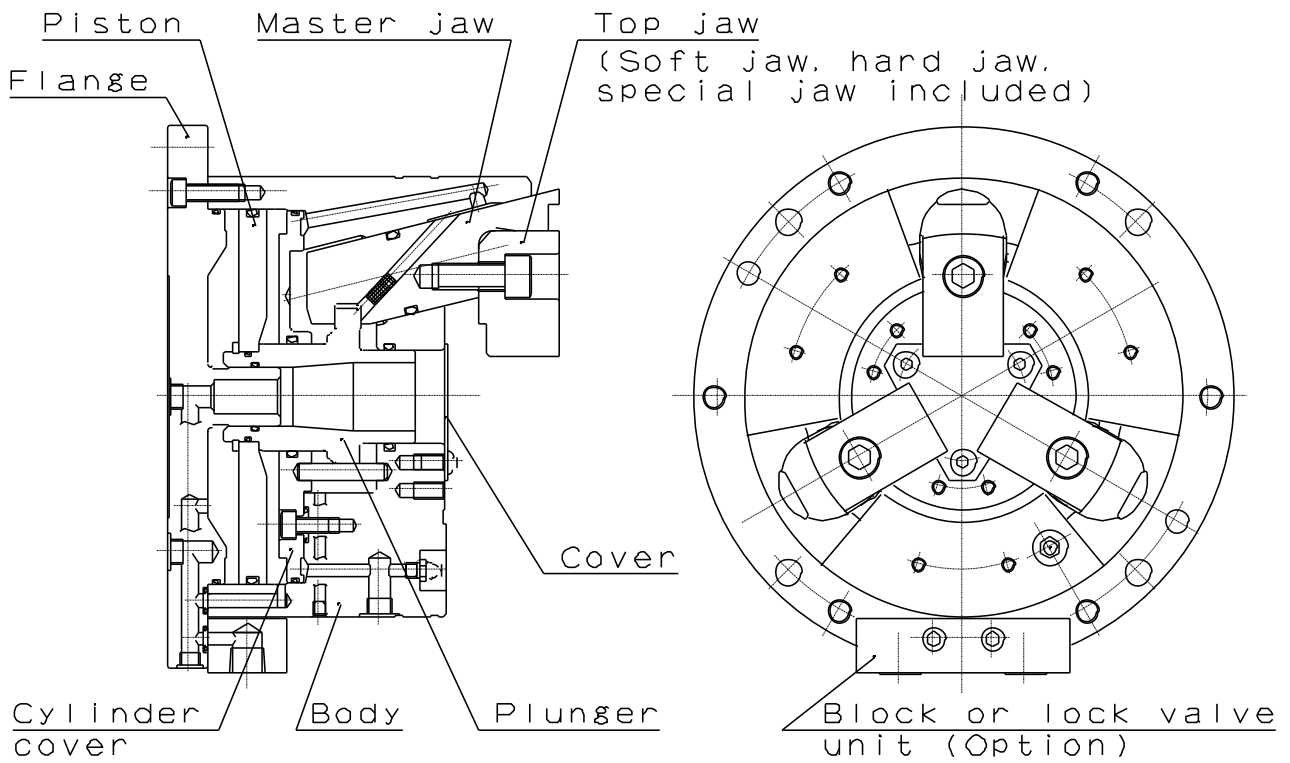


Fig.2

1-3. Scope of product

This instruction manual is for the work gripper. Other than information about the work gripper, it is mentioned about optional article (A lock valve unit LV-3 and manual operated valve AV-02S).

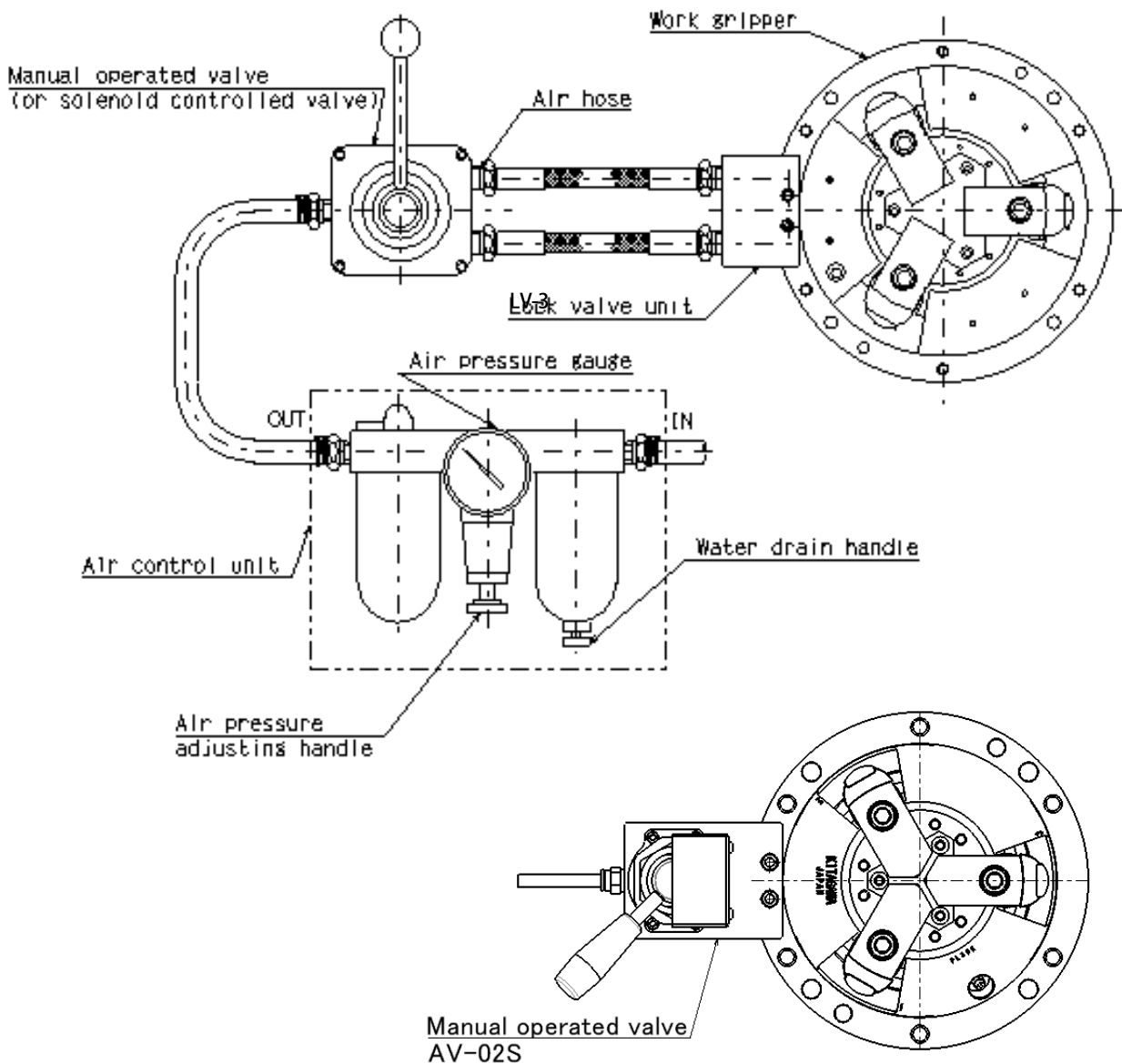


Fig.3

! WARNING

- To prevent the work from flying, safe design, maintenance and erroneous action prevention of the pneumatic system to maintain the gripping force of the work gripper is extremely important. Thoroughly read the "Important Safety Precautions" on and after page 11 in this manual.
- As for the other pneumatic products, follow the instruction manual for these products.

1-4. Parts list

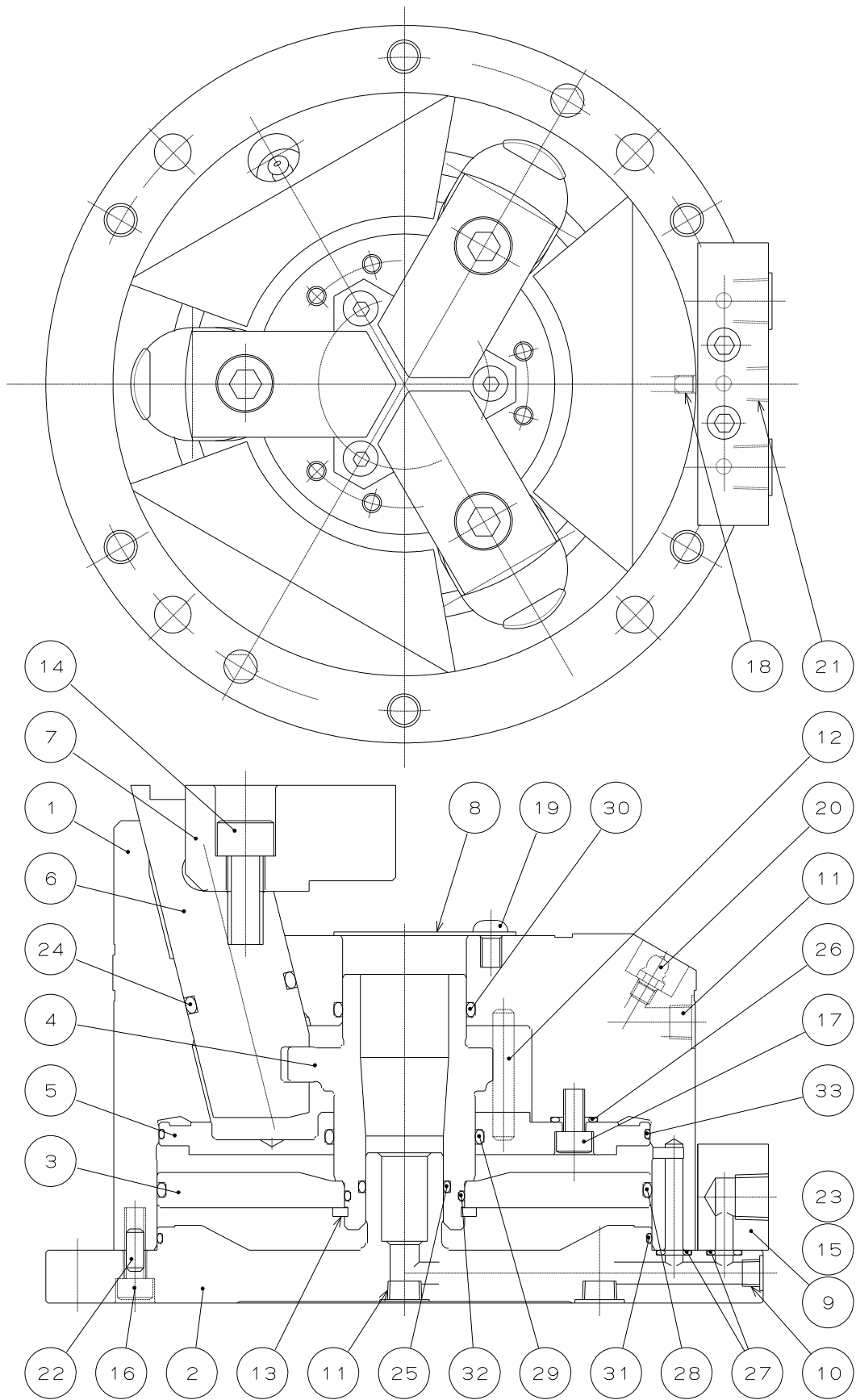


Fig.4

Table 1

No.	Part name	Quantity	No.	Part name	Quantity
1	Body	1	18	Set screw	1
2	Flange	1	19	Socket head button screw	3
3	Piston	1	20	Grease nipple	1
4	Plunger	1	21	Orifice plug	1
5	Cylinder cover	1	22	Parallel pin	1
6	Master jaw	3	23	O-ring	3
7	Soft jaw	3	24	O-ring	3
8	Cover	1	25	O-ring	1
9	Block	1	26	O-ring	6
10	Plug C	3	27	O-ring	1
11	Plug D	4	28	O-ring	1
12	Parallel Pin	1	29	O-ring	1
13	Retaining Ring	1	30	O-ring	1
14	Jaw attaching bolt	3	31	O-ring	1
15	Socket head cap screw	2	32	O-ring	1
16	Socket head cap screw	5 or 8	33	O-ring	1
17	Socket head cap screw	6			

Table 2 Consumable parts

No.	Part name	PLS04	PLS06	PLS08
23	O-ring	JIS 2041 P7	JIS 2041 P7	JIS 2041 P7
24	O-ring	JIS 2041 P16	JIS 2041 P26	JIS 2041 P34
25	O-ring	JIS 2041 P11	JIS 2041 P22	JIS 2041 G35
26	O-ring	JIS 2041 P9	JIS 2041 P10	JIS 2041 P10
27	O-ring	NOK S7	JIS 2041 P7	JIS 2041 P7
28	O-ring	JASO 3080	JIS 2041 G135	JIS 2041 G175
29	O-ring	JIS 2041 P24	JIS 2041 G40	JIS 2041 G55
30	O-ring	JASO 2028	JIS 2041 G35	JIS 2041 G55
31	O-ring	JIS 2041 G80	NOK S135	AS568-262
32	O-ring	NOK S18	JIS 2041 S30	NOK S46
33	O-ring	NOK S80	NOK S135	AS568-262

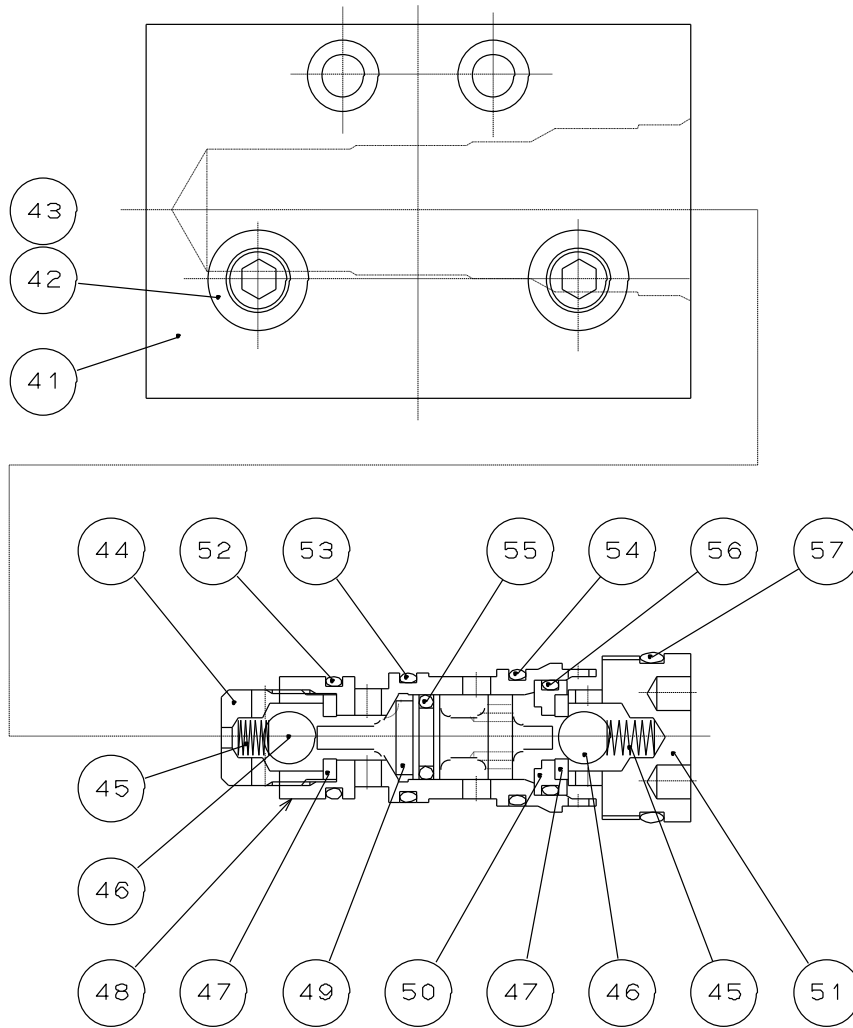


Fig.5 Lock valve unit

Table 3

No.	Part name	Quantity	No.	Part name	Quantity
41	Block	1	51	Plug	1
42	Seal washer	2	52	O-ring JASO 1015	1
43	Cap screw	2	53	O-ring JASO 1016	1
44	Cap	1	54	O-ring JASO 1017	1
45	Spring	2	55	O-ring JIS B2401 P9	1
46	Ball $\phi 8$	2	56	O-ring JASO 1014	1
47	Valve seat	2	57	O-ring JASO 1021	1
48	Housing	1	58	Hex. key 5	1
49	Pilot spool	1	59	Cap screw M6 \times 50	2
50	Ring	1	60	Air pressure gauge	1

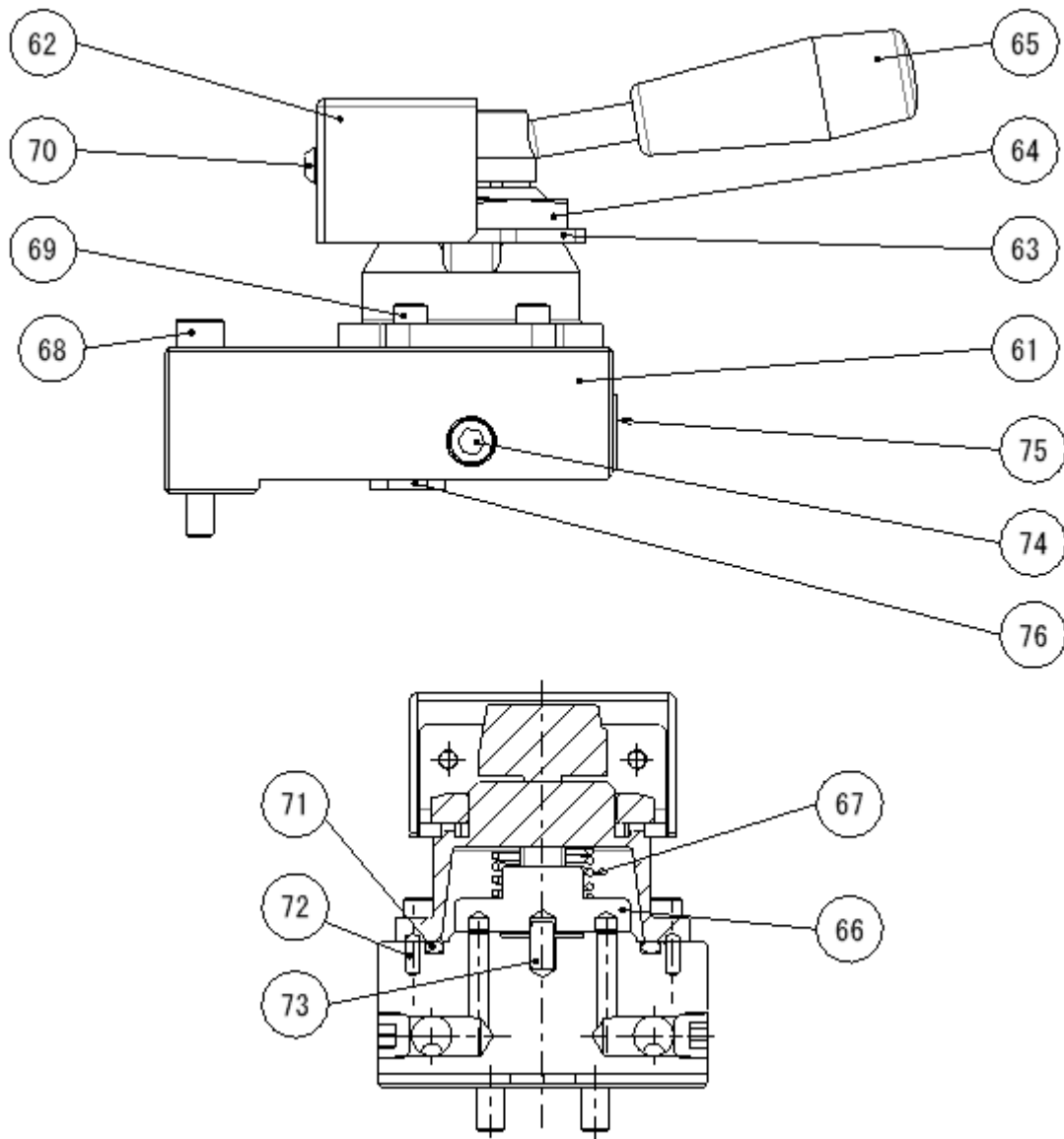


Fig6. Manual operated valve

Table 4

No.	Part name	Quantity	No.	Part name	Quantity
61	Baseplate	1	69	Cap screw M4 × 12	4
62	Handle cover	1	70	Cap screw M4 × 8	2
63	panel	1	71	O-ring G 45	1
64	Lock nut	1	72	Parallel pin 3x8	2
65	Hand valve	1	73	Parallel pin 5x10	1
66	Resin parts	1	74	Plug	4
67	Spring	1	75	Nylon cap	1
68	Cap screw M6 × 40	2	76	Silencer	1

※We do not sell parts only.

2. Important Safety Precautions

Important safety precautions are summarized below. Please read this section before first starting to use this product.



DANGER

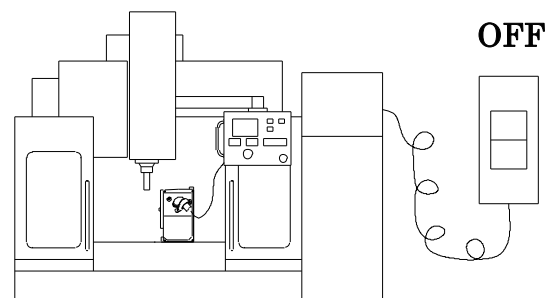
Failure to follow the safety precautions below will result in serious injury or death.



Turn off main power supply before attaching, inspecting or replacing work gripper, and before adding oil.

For All Users

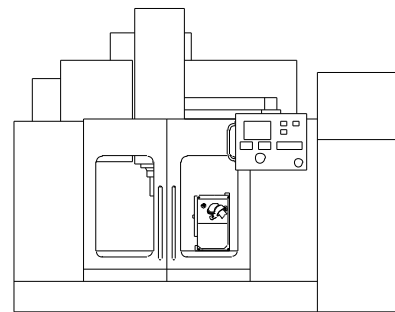
- The machine tool may start rotation suddenly, and a part of the body or clothing may be caught.



Close door before machining.

For All Users

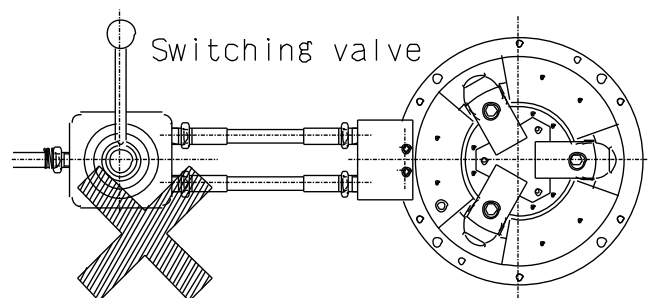
- If the door is not closed, you may touch the tools or the work gripper, or the work may fly out, which is very dangerous. (In general, the safety interlock function which allows machining only when the door is the manual mode or the test mode)



During machining, do not operate switching valve.

For All Users

- This is dangerous as the work will fly out.





Important Safety Precautions



DANGER

Failure to follow the safety precautions below will result in serious injury or death.



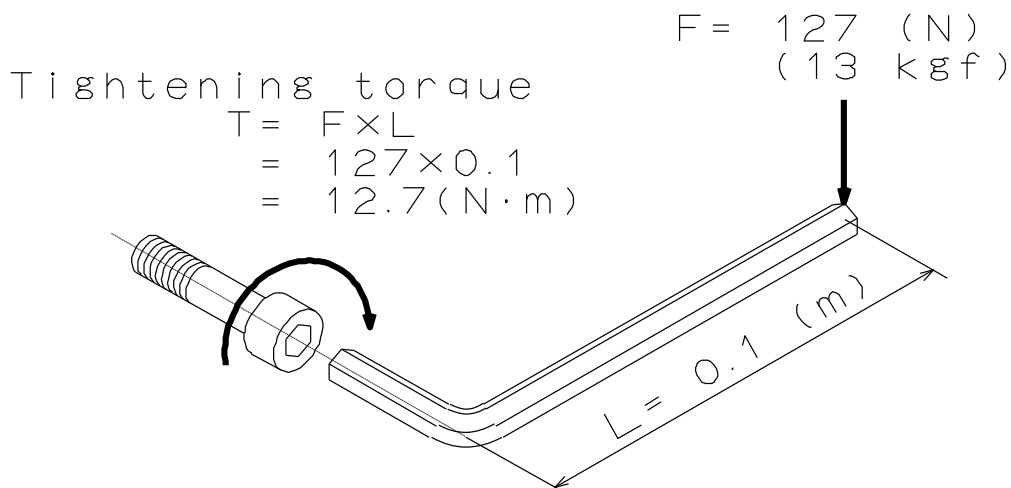
Always tighten the bolts at the specified torque. If the torque is insufficient or excessive, the bolt will break, which is dangerous as the work gripper or work will fly out. Use the bolts attached to the work gripper, and do not use bolts other than these.

For All Users

- If the torque is insufficient or excessive, the bolt will break, which is dangerous as the work gripper or work will fly out.
- You cannot control the torque by a hex key. You must use a torque wrench for torque control.

Specified torque for socket head cap screw

Bolt size	Tightening torque	
M5	7.5	N·m
M6	13	N·m
M8	33	N·m
M10	73	N·m
M12	107	N·m
M14	171	N·m
M16	250	N·m
M20	402	N·m
M22	539	N·m



- Tightening torque is moment of force when you tighten a bolt. Tightening torque = $F \times L$.



Important Safety Precautions



WARNING

Failure to follow the safety precautions below could result in serious injury or death.



Use a lock valve (safety valve, check valve) incorporated in case of sudden pneumatic pressure drop due to blackout, malfunction, etc. Further, use a solenoid valve with a circuit that retains the gripping position when no current is carried.

(Refer to page 26)

For Machine Tool Manufacturers

- If the pneumatic pressure suddenly drops due to blackout or malfunction, etc., this is dangerous as work will fly out.
- Lock valve retains the pneumatic pressure inside the cylinder temporarily, when the pneumatic pressure suddenly drops due to blackout or malfunction, etc. We prepare for the lock valve unit for exclusive use of the work gripper optionally.



When the protrusion of the work is long, support it with the steady rest or center.

For All Users

- If the protrusion is long, the tip of the work can turn and the work fly out.



Do not use the work gripper on the lathe.

For All Users

- Gripping force is short by centrifugal force, or the work gripper may break and the work gripper or work could fly out.



Important Safety Precautions



WARNING

Failure to follow the safety precautions below could result in serious injury or death.

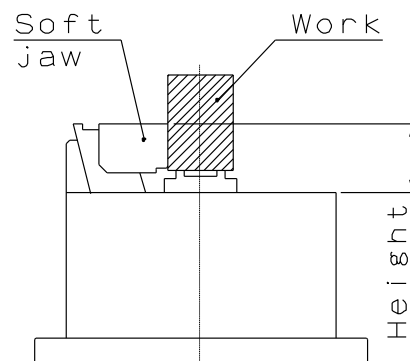


Use neither jaw that is taller jaw than standard jaw. The air pressure must not exceed the maximum air pressure, and the oil pressure must not exceed the maximum oil pressure.

(Refer to pages 16-18)

For All Users

- The work gripper will break and the work gripper and work will break and fly out.



Determine the gripping force required for processing by the machine tool manufacturer or user, and check that the required gripping force is provided before processing.

(Refer to pages 16-17)

For All Users

- Adjust the pneumatic pressure to obtain the required gripping force. If the gripping force is insufficient, this is dangerous as the work will fly out. Adjust the steering wheel of the reducing valve, and set it to prescribed pressure. Afterwards, tighten the lock nut, and prevent the setting pressure from carelessly changing.



Always fill lubricator with oil up to proper level. Periodically drain water in the filter. (Refer to each instruction manual for the details.)

For All Users

- Rust may occur in the cylinder, the work scatters due to the defective operation and the decrease of the gripping force, and it is dangerous.



Important Safety Precautions



WARNING

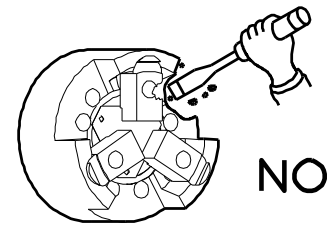
Failure to follow the safety precautions below could result in serious injury or death.



Do not modify the work gripper in a way not permitted by the manufacturer.

For All Users

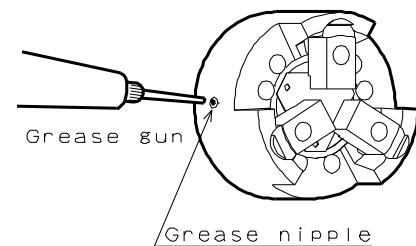
- It may not only break the work gripper but the work gripper and the work may fly out, which is dangerous.
- If you attach a locator or jig on the work gripper body surface, only process work in an acceptable range (Refer to pages 24-25).



Periodically supply adequate grease (Refer to page 27). Turn off power before adding grease.

For All Users

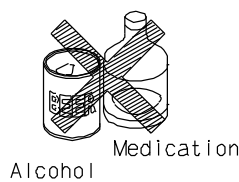
- Insufficient grease supply lowers the gripping force, causes operation failure due to lower hydraulic pressure, lowers the gripping precision, and causes abnormal wearing and seizing, etc.
- This is dangerous as the work could fly out from a drop in the gripping force.



Do not operate the machine after drinking alcohol or taking medication.

For All Users

- Dangerous since these lead to operation mistakes and misjudgment.



Do not operate the machine wearing gloves, a necktie, and other loose clothing or jewelry.

For All Users

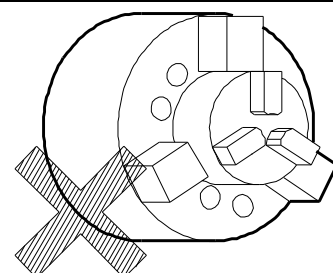
- Dangerous since it will be caught.



Do not grip a chuck with a chuck.

For All Users

- Because it is easy to confuse the specifications of each work gripper and the protrusion become long and is apt to exceed the specifications, it is apt to exceed the specifications of the base chuck. The work gripper may break and the work gripper or work could fly out.



3. Specifications

3-1. Specifications

Table 5

Type		PLS04	PLS06	PLS08
Plunger stroke	mm	6	10	10
Jaw stroke (in diameter)	mm	3	5	5
Gripping force (Air pressure : 0.6MPa)	kN	6.7	18.5	37
Gripping force (Oil pressure : 1.3MPa)	kN	16	40	80
Gripping range (outside diameter gripping)	mm	φ5~50	φ8~69	φ8~89
Mass (standard soft jaw included)	kg	7.4	18	33
Nominal air pressure	MPa	0.2 ~ 0.7		
Max air pressure	MPa	0.7		
Nominal oil pressure	MPa	0.2 ~ 1.3		
Max oil pressure	MPa	1.3		
Air consumption (Plunger stroke 5mm, 0.6MPa)	NI	0.22	0.54	0.93
Storing temperature / Operating temperature		-20 ~ +50 °C / -10 ~ +40 °C		

※When storing this product, the product should be subjected to the antirust treatment and stored in a place free from wetting, condensation, or freeze.

※We recommend using pneumatic pressure when operating at 0.2 to 0.7 MPa. Using hydraulic pressure at 0.2 to 0.7 MPa will result in slower operation time.

3-2. Relationship between pressure and gripping force

1. Gripping force

The work gripper has a mechanism to convert air or oil pressure from the built-in cylinder to gripping force. The gripping force specified in the specification is the value that the air pressure is 0.6 MPa, or the oil pressure is 1.3MPa.

However, the gripping force is different depending on the state of grease lubrication, grease in use, height of the jaw, etc.

The gripping force specified in the specification is the value under the following conditions:

- The Kitagawa standard soft jaw is used as the jaw.
- The attaching bolts of the soft jaw are tightened at the specified torque. (Refer to page 12)
- The numerical values are obtained with the Kitagawa gripping force meter . The gripping position of the gripping force meter is at a position 1/2 of the height of the soft jaw top surface (height from the chuck surface to the top surface of the jaw).
- CHUCK GREASE PRO is used. (Refer to page 27).
- The air pressure is 0.6 MPa, or the oil pressure is 1.3MPa.

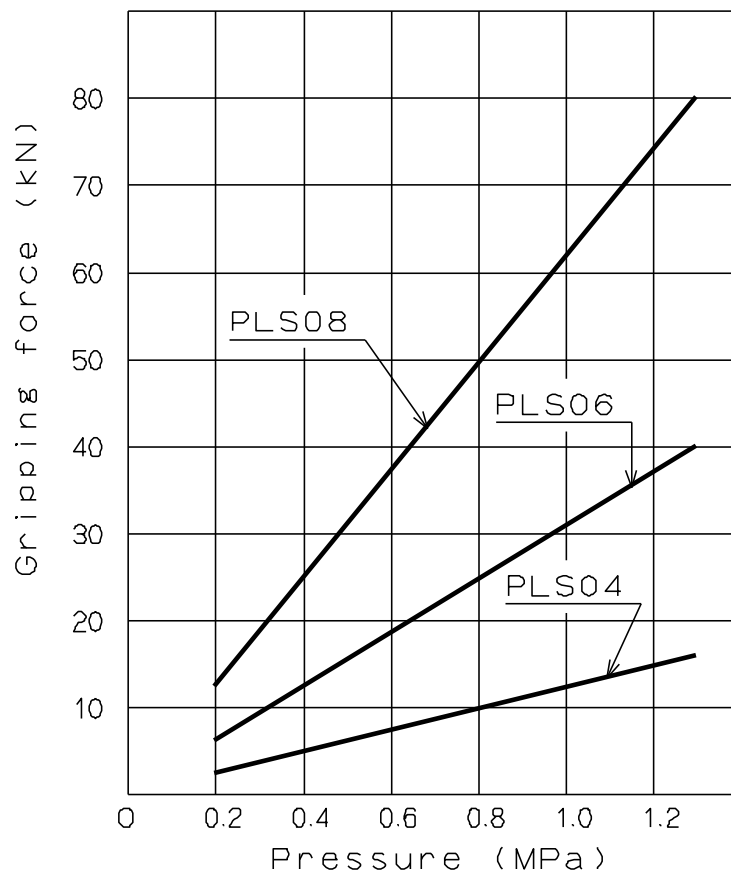


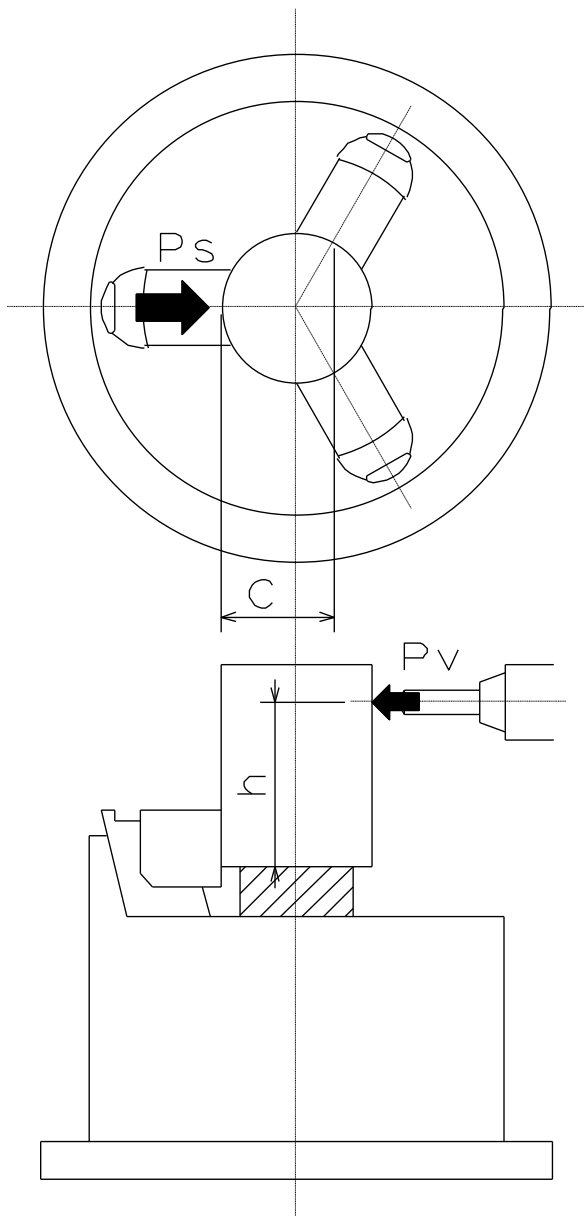
Fig.7

WARNING

- Use neither jaw that is taller jaw than standard jaw. The moment hanging to the work gripper becomes large when you use taller jaw and this is dangerous as the work gripper and work will fly out.

Cutting condition

As a review method of cutting condition, the following shows a calculation example in the case where the moment load is put on the workpiece by a drilling. The final cutting condition, however, must be determined by a test cutting.



$$\frac{\mu \times P_s \times C}{P_v \times h} = S > 2.5$$

P_s : Gripping force per a jaw

μ : Gripping surface friction coefficient between jaw and workpiece. In general, 0.1 is used when both are smooth surfaces.

P_v : Drilling thrust

S : Factor of safety

Fig.8

4. Forming Soft Jaw

Prepare the jaw that has the shape, dimensions, accuracy, plane roughness and quenching suitable for processing the work-piece. We recommend following the following method for manufacturing the jaws.

- Forming standard soft jaw on the machine and using a raw material as is. Although it is inferior in durability on gripping face, you can manufacture product immediately.
- Forming standard soft jaw roughly and quenching their gripping face, then finishing on the machine. This is suitable for a mass production, because it excels in durability of the gripping face.
- We recommend you request KITAGAWA for manufacturing, if you manufacture a special shape jaw from scratch without using soft jaw.

4-1. Attachment of jaw



- **Use the bolts attached to the work gripper, and do not use other bolts. However, if you must use other bolts not provided by Kitagawa, use bolts that have at least a strength classification of 12.9 (10.9 for M22 or more) and be sure they are long enough.**
- **Do not rotate the work gripper so that the jaw attaching bolt is loosened causing the jaw to fly out.**
- **Never use the chuck when the work-piece is clamped near the stroke end more than 75% of the stroke. When the work-piece is clamped near the stroke end, because the work-piece is not completely gripped or the gripping force is insufficient, this is dangerous as the work will fly out.**
- **Always tighten the bolts at the specified torque. If the torque is insufficient or excessive, the bolt will break, which is dangerous as the work gripper or work will fly out.**

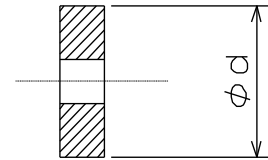
Table 6

Bolt size	Tightening torque	
M5	7.5	N·m
M6	13	N·m
M8	33	N·m
M10	73	N·m
M12	107	N·m
M14	171	N·m
M16	250	N·m
M20	402	N·m

4-2. Forming soft jaw

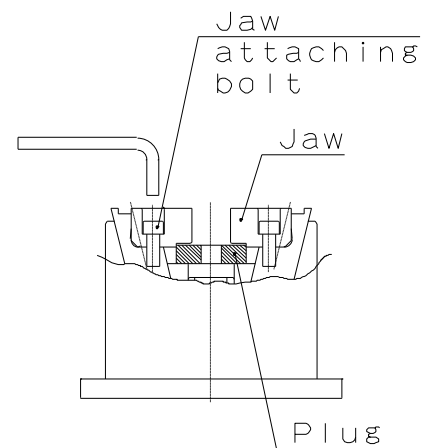
1. Preparation of the plug for forming

- Prepare the plug for forming. The surface roughness of the plug outside diameter is to be approximately 25s, and make a shape with sufficient thickness which does not distort.
- Set outer diameter dimension of plug to grip it around the middle of jaw stroke.
- It is convenient to process tapping in the center part of the plug and to guide with a bolt, etc.



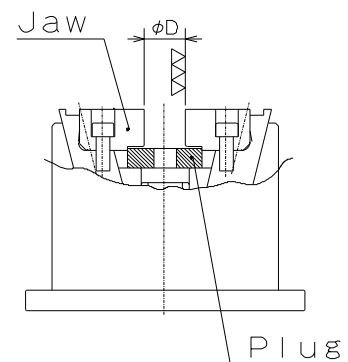
2. Gripping of the plug for forming

- Jaw and locator are detached.
- Fit the plug for forming to the work gripper and fix the jaws temporarily with jaw attaching bolt. Set hydraulic pressure to low and grip the plug. Then push the plug to chuck evenly so that the plug does not tilt.
- Tighten the jaw attaching bolts by specified torque in a state as is. If the temporary jaws fixing is not tight enough, the jaw are lifted when gripping the plug. The plug will not be set correctly.
- Unclamp the chuck and set the hydraulic pressure to the working condition. Then grip the plug again. Then push the plug to chuck evenly so that the plug does not tilt.



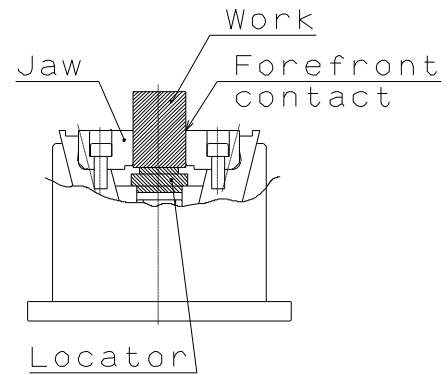
3. Forming

- Process the gripping part (dimension ϕD) of the work in the state that the plug is kept gripped. The ϕD part is to be approximately the same diameter (H7) as the diameter of the gripping part of the work, and process to be surface roughness at 6s or less.
- Set the hydraulic pressure during forming the same as during processing of the work, or slightly higher.
- When the plug distorts, lower the hydraulic pressure or change the plug into a shape which does not easily distort



4. Trial cutting

- Remove the plug for forming and attach the locator and the jigs necessary, then grip the work to check the jaw stroke.
- Implement trial cutting to check the process precision and that there is no slip, etc.
- When the gripping contact of the jaw is stronger in its forefront part, the work-piece can be gripped better with less runout at end of the work-piece.



WARNING

- **Grip the plug for forming when you form the soft jaw. If you do not, the jaw is rotated by the cutting force, this is dangerous as the jaw will fly out.**

NOTICE

- The gripping force, retracting motion and accuracy become stable when the gripping center height becomes as low as possible.
- When the jaw is not finished on the machine or it is finished on another machine, the contact for the work-piece becomes worse, thus resulting in an unstable retracting motion or reducing the gripping accuracy.
- When finishing the jaw without touching the plug for forming to the chuck surface or locator datum end face, the gripping accuracy may be impaired.
- When the gripping position of the plug for forming is near the gripping face of work-piece as much as possible, the gripping accuracy becomes stable.
- When the jaw finished on the machine is removed from the work gripper once, the gripping accuracy becomes low as compare with when it is attached as is.
- Do not mistake the numbers marked on jaw.
- If the rigidity of the plug for forming is insufficient, the gripping accuracy becomes low or stroke position becomes out of order.

5. Usage

This product is a device to fix a work-piece when it is processed by the rotary table or the machining center. A built-in cylinder closes the jaw and fixes a work-piece so that it does not move during processing. The chuck opens the jaw after having processed it and remove a work-piece.

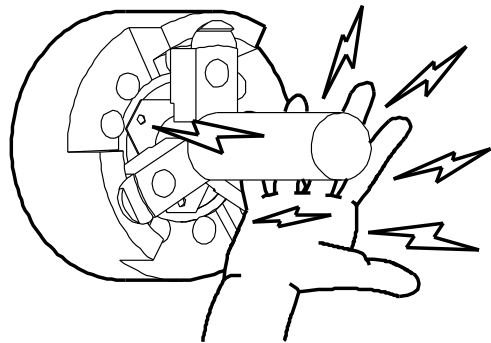
NOTICE

- When replacing the top jaw, carefully clean the serration part with the master jaw, and the engagement part of the T nut. Failure to do this may cause a precision failure.
- Set the air pressure according to the shape of the work and the cutting conditions. Pipe shape work, etc., may be distorted if they are tightened at a high gripping force.

5-1. Precautions during gripping work with work gripper

DANGER

- When gripping a work with the chuck, do not get fingers or hands become caught. This could cause crushed or cut fingers and hands.



5-2. Precautions during gripping work in irregular shape

WARNING

- Cast metal, pitched shape or taper shape cannot be gripped.
- If the protrusion of the work is long, support it with a center or the steady rest. If the protrusion is long the tip of the work turns, and this is dangerous as the work will fly out.

5-3. Precautions related to usage of jaw



- If a soft jaw other than one made by **Kitagawa Corporation** is used, the engagement will be inferior, and the master jaw will be deformed, the gripping precision will worsen, and the work will fly out due to gripping failure, which is dangerous.
- Do not use the soft jaw by welding to join for extension. The jaw will break due to insufficient strength and the serration part will become distorted due to welding. As a result, the engagement will worsen, the serration crests will break, and this is dangerous as the work will fly out.

5-4. Precautions related to processing



<1> Interference, contact, impact

- Before starting work, check that the top jaw, locator, work, etc., and the tool and the tool post, etc., do not interfere at low rotation and then start processing.
- Do not allow anything to impact the work gripper, jaw, and the work. The work gripper will break and this is dangerous as the work gripper and work will fly out.
- If the tool and the tool post contact the work gripper or the work due to malfunction or tape mistake, etc., and impact is given, immediately stop the machining, and check that there are no abnormalities in the top jaw, master jaw, T nut and bolts of each part, etc.

<2> Coolant

- Unless coolant with a rust preventive effect is used, rust will occur inside the work gripper and gripping force drop may result. The work will fly out due to the gripping force drop and this is dangerous.

5-5. Attachment of locator and jig

The locator is required for the PLS work gripper. The PLS work gripper grips the work-piece in the radial direction and presses the work-piece to the locator simultaneously. Prepare the locator that has the dimensions, accuracy, materials and quenching suitable for processing the work-piece.

DANGER

- **Grip the work-piece after having pushed it to the locator. You can't grip the work-piece stably when you use without locator, this is dangerous as the work will fly out. (The black thin cover for the center of the chuck is not a locator. This is temporary protection for the hole.)**
- Since the runout of the locator datum end face remarkably influences the finishing accuracy of the work-piece, the datum end face requires that it has sufficient hardness and accuracy. To improve the accuracy of the datum end face, we recommend that the locator is finished with it attached to the chuck after quenching.
- In the case of attaching the locator and the jig on the chuck body surface, tap or drill a hole in the additional process range specified in Fig. 9
- Air can be supplied to the seating position by removing the orifice plug【21】from the block【9】. Air can also be supplied through the work gripper back side by first removing hole plug D【11】from the flange【2】air supply port for seating position. Also, remove the orifice plug【21】 from the block【9】 and replace it with the hole plug D【11】 that has been rewound with sealing tape to be used as a stopper.

WARNING

- **The work gripper can be modified only in the manufacturer permissible range. This will not only break the work gripper but the work gripper and work may fly out, which is dangerous.**
- **Provide a countermeasure against flying out (dwell pin, etc.) due to centrifugal force to the locator or the jig, and attach with bolts which have sufficient strength. The locator or the jig may fly out, and this is dangerous.**

Shaded part additional process possible range

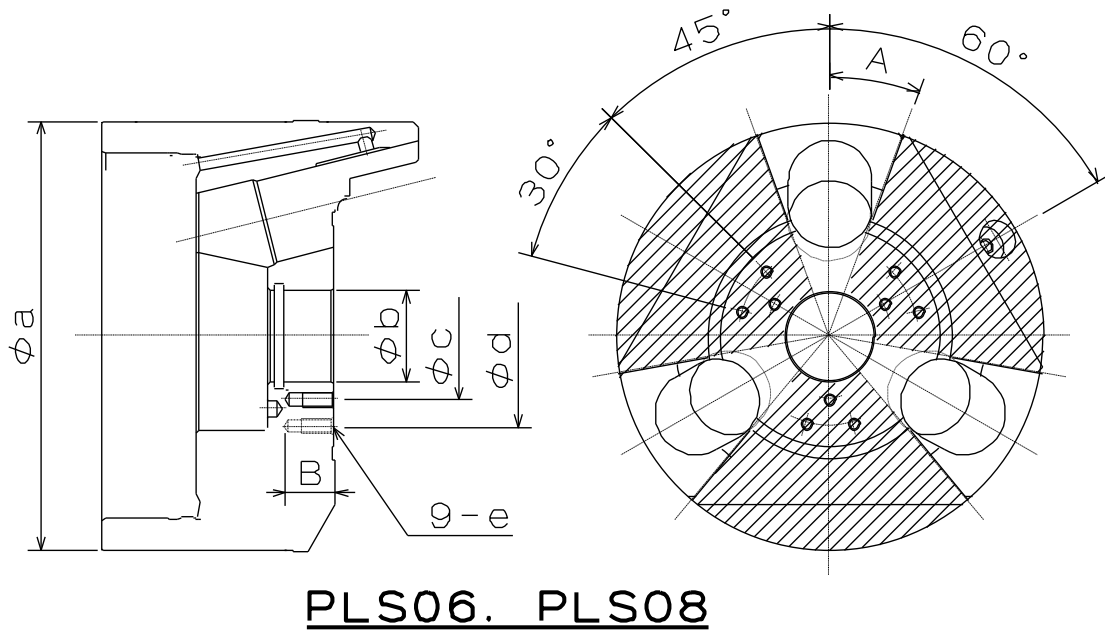
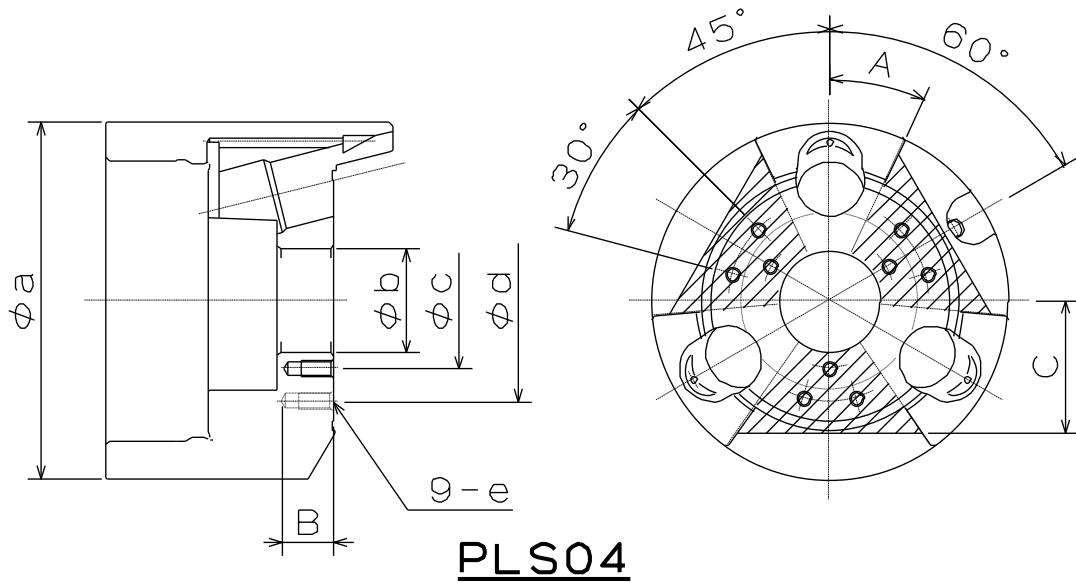


Fig.9

Table 7

Type	A	B	C	a	b	c	d	e
PLS04	25	14.5	40.5	110.1	32	42	62	M5-10
PLS06	20	17	-	165.1	35	49	70	M6-12
PLS08	20	17	-	210.1	55	71	95	M6-12

A: Additional process impossible dimension.

B: Processible depth of tapping or drilling a hole.

5-6. Precautions related to usage of lock valve unit

Lock valve unit

Lock valve retains the pneumatic pressure inside the cylinder temporarily, when the pneumatic pressure suddenly drops due to blackout or malfunction, etc. We prepare for the lock valve unit for exclusive use of the work gripper optionally.

The air pressure in the work gripper is sealed up by using the lock valve unit. Therefore, it is possible to machining a workpiece without piping.

WARNING

- If the air supply is stopped and the workpiece is held for a long time using the lock valve unit, before start of the work, measure the pressure retention time to make sure that the internal pressure does not drop. Reduction in gripping force due to the internal pressure drop causes the workpiece to fly out.
- Use the lock valve unit only by air. The lock valve unit is damaged when the oil pressure is put, this is dangerous as the work will fly.

6. Maintenance and Inspection

6-1. Periodic Inspection

- Add grease at least once a month.
- Fully stroke the jaw before starting work or upon supplying grease, and check the specified stroke.
- Always clean the chuck body or the sliding surface using an air gun, etc., at the end of work.
- Periodically drain water in the filter.
- Always fill lubricator with oil up to proper level.
- When the lock valve unit is used, confirm whether there will not be the decrease in inner pressure because of the air leakage in at least once a week. (Refer to Page 30)
- Check that the bolts of each part are not loosened at least once every 3 months.
- Disassemble and clean at least once every 6 months or every 100,000 strokes (once every 2 months or more for cutting cast metal).

6-2. Grease lubrication

1. Position to lubricate

- Lubricate using a grease gun from the grease nipple on the body periphery part.
- Read the following lubricating procedures with reference to pages 7-8.
 1. Turn off the main power of the machine before starting work.
 2. Place the plunger on the platform, positioning it forward and upward.
 3. Remove the set screw [18] on the body periphery part.
 4. Move the jaws several times without work-piece to exhaust old grease. At this time, if the coolant or cutting chips are in the chuck, disassemble and clean it. It is necessary to doubt the damage of the seal.
 5. Lubricate using a grease gun from the grease nipple [20] on the body periphery part until grease is exhausted from the hole.
 6. Keep in item 2 above, clamp and unclamp a couple of times without work piece to discharge extra grease.
 7. Install the set screw [18] certainly.
 8. Clamp and unclamp a couple of times without work piece again, and check that the No.1 master jaw fully stroke.
- It is convenient to use grease supply port (Rc1/8) on the body periphery part if you arrange and use a lot of work grippers.

2. Grease to use

- Use the designated grease specified in Table 8. If grease other than the designated grease is used, sufficient effect may not be obtained.

Table 8

Genuine product	CHUCK GREASE PRO	Kitagawa genuine product (Kitagawa distributor of each country)
Conventional product	Kitagawa chuck grease	Conventional product
	Molykote EP Grease	TORAY Dow Corning (only inside Japan)
	Chuck EEZ grease	Kitagawa-Northtech Inc. (North American region)
	MOLYKOTE TP-42	Dow Corning (Europe, Asian region)
	Klüberpaste ME31-52	Klüber lubrication (worldwide)

3. Frequency of lubrication

- Add grease at least once a month.
- In the case of high rotation or in the case of using a large amount of water soluble coolant, increase the frequency of lubrication according to the usage conditions.



- **To keep the chuck running in the best condition for a long time, adequate grease lubrication is necessary. Insufficient grease lubrication causes a drop in the gripping force, operation failure at low hydraulic pressure, drop in gripping precision, abnormal wearing, seizing, etc. The work will fly out due to a drop in the gripping force and this is dangerous.**

4. Safety information about grease and anti-rust oil

Applicable range

- Designated grease
- Antirust agent applied to the product at the delivery.

First aid measures

After inhalation: Remove victim to fresh air. If symptoms persist, call a physician.

After contact with skin: Wash off with mild cleaners and plenty of water. If symptoms persist, call a physician.

After contact with eyes: Rinse with plenty of water. If symptoms persist, call a physician.

After ingestion: If large amounts are swallowed, do not induce vomiting. Obtain medical attention.

- Please refer to each MSDS about the grease and the anti-rust oil which you prepared.

6-3. Disassembling

Disassembling procedures

Read the following disassembling procedures with reference to pages 7-9.

1. Turn off the main power of the machine before starting work.
2. If the lock valve unit is used, loosen slowly two cap screws [43] while bleeding the air gradually from the inside, and after making sure that the air is expelled completely, remove the screws.
3. Loosen the jaw attaching bolt [14] and remove the soft jaw [7].
4. Remove the locator or jigs on the work gripper surface.
5. Loosen the socket head cap screw [16] and remove the flange [2].
6. Remove the Retaining ring [13] and remove the piston [3].
7. Loosen the socket head cap screw [17] and remove the cylinder cover [5].
8. Remove the Parallel pin [22].
9. Rotate by 60 degree with the plunger [4] pushed in the maximum, then pull it out after removing the combination with the master jaw [6].
10. Remove the master jaw [6].
11. Assemble again while sufficiently coating the recommended grease in the reverse procedures of disassembling. At this time, pay sufficient attention so as not to make a mistake in the numbers of the body [1], master jaw [6], and the plunger [4].
Moreover, exchange O-rings of each part if necessary.
12. Refer to page 33 about the installation procedure. (8. Attachment).



- **Use an eyebolt when attaching and detaching the chuck to and from the machine, as there is a danger of injury or damage if the work gripper drops.**

Size	Eyebolt
4"	M8
6"	M10
8"	M10

 **WARNING**

- **Be sure to remove the eyebolt after use. If the machining starts without removing the eyebolt, it will interfere with a tool, causing the bolt or tool to fly out.**
- **Disassemble and clean the work gripper at least once every 6 months or every 100,000 strokes (once every 2 months or more for cutting cast metal). If cutting powder or other substances stagnate inside the work gripper, it will lead to insufficient stroke and a drop in the gripping force, and this is dangerous as the work will fly out. Check each part carefully and replace any part that is worn or cracked.**
- **Before disassembling the work gripper, remove the cap screw to bleed the air. Loosen slowly the cap screw while bleeding the air gradually from the inside, and after making sure that the air is expelled completely, remove the cap screw. With internal pressure applied, disassembling the work gripper causes the parts to fly out.**
- **After inspection, apply sufficient grease in the designated areas and reassemble.**
- **After assembling, measure the gripping force according to the method on page 17, and check that the specified gripping force is obtained.**
- **If you stop the machine for a long period of time, remove the work from the machine. If you don't, the work can drop due to a drop in the air pressure or the cylinder can stop or malfunction.**
- **If you stop the machine or store the work gripper for a long period of time, add grease to prevent rust.**

6-4. Inspection of lock valve unit

When the lock valve unit is used, confirm whether there will not be the decrease in inner pressure because of the air leakage in at least once a week. Read the following procedures with reference to pages 7-9.

1. Loosen slowly two cap screws [43] while bleeding the air gradually from the inside, and after making sure that the air is expelled completely, remove the cap screws.
2. Install the pressure gauge [60] and set it to 0.5 – 0.6 MPa, and stop the air supply.
3. If the pressure drop per hour exceeds 0.05MPa, the lock valve unit must be repaired or replaced.

WARNING

- Loosen slowly the cap screw while bleeding the air gradually from the inside, and after making sure that the air is expelled completely, remove the cap screw. With internal pressure applied, disassembling the work gripper causes the parts to fly out.
- If the air supply is stopped and the workpiece is held for a long time using the lock valve unit, before start of the work, measure the pressure retention time to make sure that the internal pressure does not drop. Reduction in gripping force due to the internal pressure drop causes the workpiece to fly out.

7. Malfunction and Countermeasures

7-1. In the case of malfunction

Check the points specified in the table below and take the appropriate countermeasure.

Table 9

Defective	Cause	Countermeasure
The work gripper does not operate.	The work gripper inside will break.	Disassemble and replace the broken part.
	The sliding surface is seized.	Disassemble, correct the seized part with oilstone, etc., or replace the part.
	The cylinder is not operating.	Check the piping and the electric system, and if there is no abnormality, disassemble and clean the cylinder.
	Malfunction of lock valve unit.	Repair or replace the lock valve unit.
Insufficient stroke of the jaw.	A large amount of cutting powder is inside. Rust might occur.	Disassemble and clean.
The Work slips.	The stroke of the jaw is insufficient.	Adjust so that the jaw is near the center of the stroke when gripping the work.
	The gripping force is insufficient.	Check that the correct hydraulic pressure is obtained.
	The forming diameter of the top jaw is not consistent with the work diameter.	Form again based on the correct forming method.
	The cutting force is too large.	Calculate the cutting force and check that it is suitable for the specification of the work gripper.
	Insufficient grease lubrication	Supply grease from the grease nipple, and open and close the jaw several times without gripping a work.
Precision failure.	The outer periphery of the work gripper is running out.	Check the end surface run-out and the outer periphery, and retighten the attaching bolts.
	Dust is attached on the attaching part of the master jaw and the top jaw.	Remove the top jaw, and clean the attaching part thoroughly.
	The attaching bolt of the top jaw is not tightened sufficiently.	Tighten the top jaw attaching bolt at the specified torque. (Refer to page 19)
	The forming method of the soft jaw is inappropriate.	Is the plug for forming parallel to the work gripper end surface? Is the plug for forming not deformed due to the gripping force?
	The height of the top jaw is too high, the top jaw is deformed, the top jaw attaching bolt is elongated.	Lower the height of the top jaw. (Replace it with the standard size) or check the gripping contact surface and make it uniform.
	The gripping force is too large leading to the work being deformed.	Lower the gripping force in the range possible to process to prevent deformation.

**WARNING**

- If the work gripper failed due to a seizure or breakage, remove the work gripper from the machine, following the disassembly steps in page 28. When the work gripper cannot be removed due to a blockage of workpiece, do not disassemble forcibly but please contact us or our agent.
- If these countermeasures do not correct the problem or improve the situation. Immediately stop using the machine. Continuous use of a broken product or a defective product may cause a serious accident by the chuck or the work flying out.
- Only experienced and trained personnel should do repairs and fix malfunctions. Repair of a malfunction by a person who has never received instruction from an experienced person, the distributor or our company may cause a serious accident.

7-2. Where to contact in the case of malfunction

In the case of malfunction, contact the distributor where you purchased the product or our branch office listed on the back cover.

For Machine Tool Manufactures

Following pages are described for machine tool manufactures (personnel who attach a chuck to a machine). Please read following instruction carefully when you attach or detach a chuck to machine, and please sufficiently understand and follow the instructions for safe operation.

8. Attachment

8-1. Air piping

8-1-1. Outline drawing of attachment

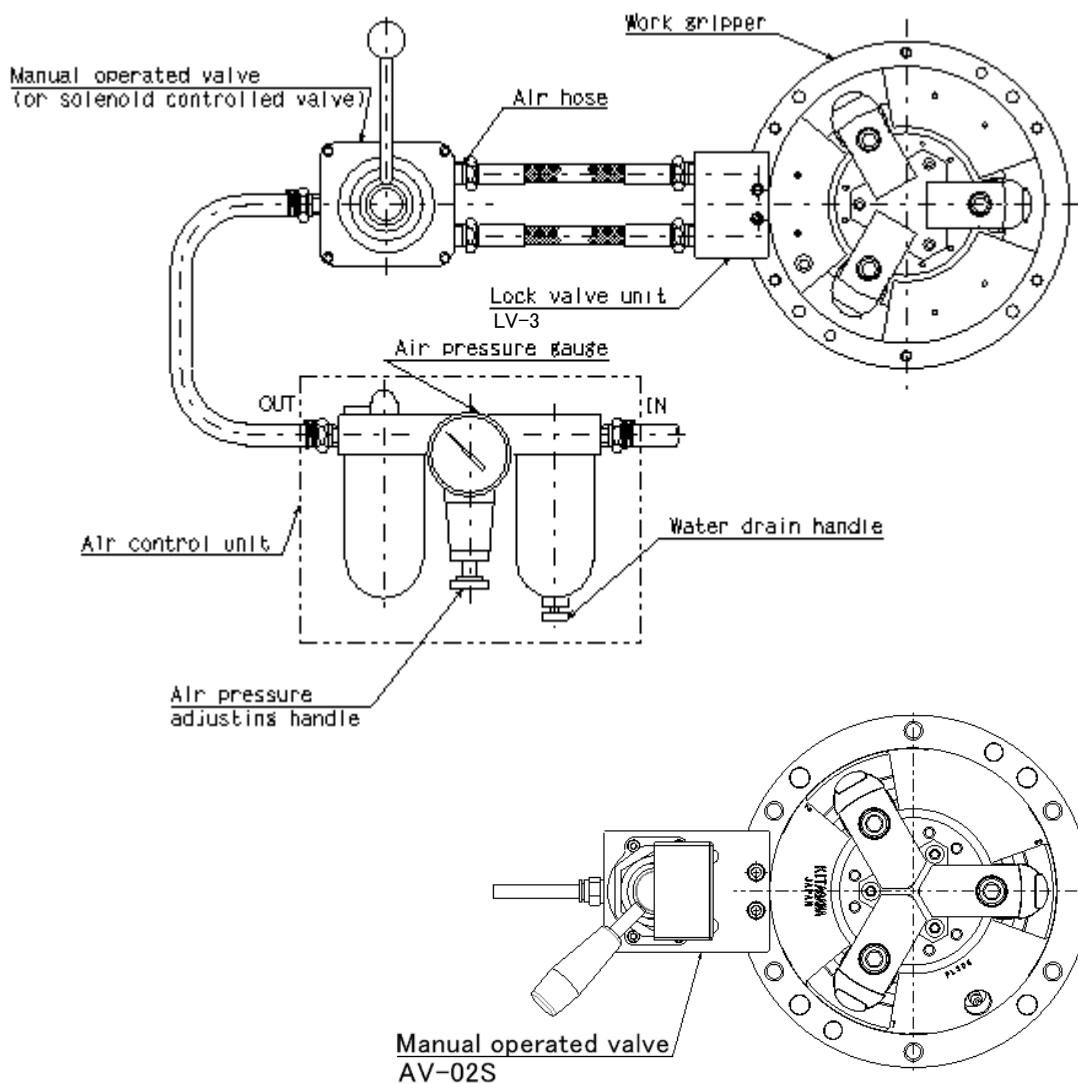


Fig.10

8-1-2. Piping

- Connect the pipe to the air supply port at the block or work gripper bottom. Blind the port on the side not used. (See Fig.14)
- To prevent the pressure drop and flow rate drop, use the pipe of Rc1/8 or larger size. Also, use the minimum number of elbows.
- Air control unit should be located near the work gripper as much as possible.
- Braided air hose should be used between the switching valve and the work gripper.

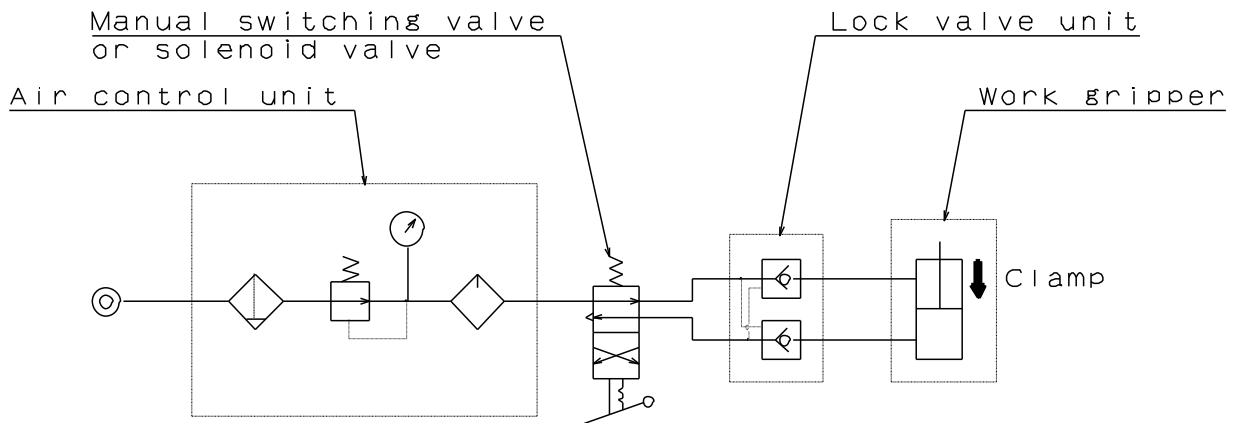


Fig.11

! WARNING

- Use a solenoid valve with a circuit that retains the gripping position when no current is carried. If the pneumatic pressure suddenly drops due to blackout or malfunction, etc., this is dangerous as work will fly out.
- During the piping, remove dust completely in the piping. Presence of dust in the piping causes air leakage and then the workpiece to fly out.

8-2. Attachment of option

We prepare for the lock valve unit LV-3 and manual operated valve AV-02S for exclusive use of the work gripper optionally. Use a lock valve (safety valve, check valve) incorporated when preparing for sudden pneumatic pressure drop due to blackout, malfunction, etc.

Attaching procedures of lock valve unit LV-3

Read the following attaching procedures with reference to pages 7-9.

1. Loosen the cap screw [15] and Remove the block [9].
2. Confirm the O-ring [27] exists, and install the lock valve unit with the cap screw [59].

Attaching procedures of manual operated valve AV-02S

Read the following attaching procedures with reference to pages 7-10.

1. Loosen the cap screw [15] and Remove the block [9].
2. Confirm the O-ring [27] exists, and install the lock valve unit with the cap screw [68].
3. Use the pipe of Rc1/4.

8-3. Oil piping

8-1-1. Outline drawing of attachment

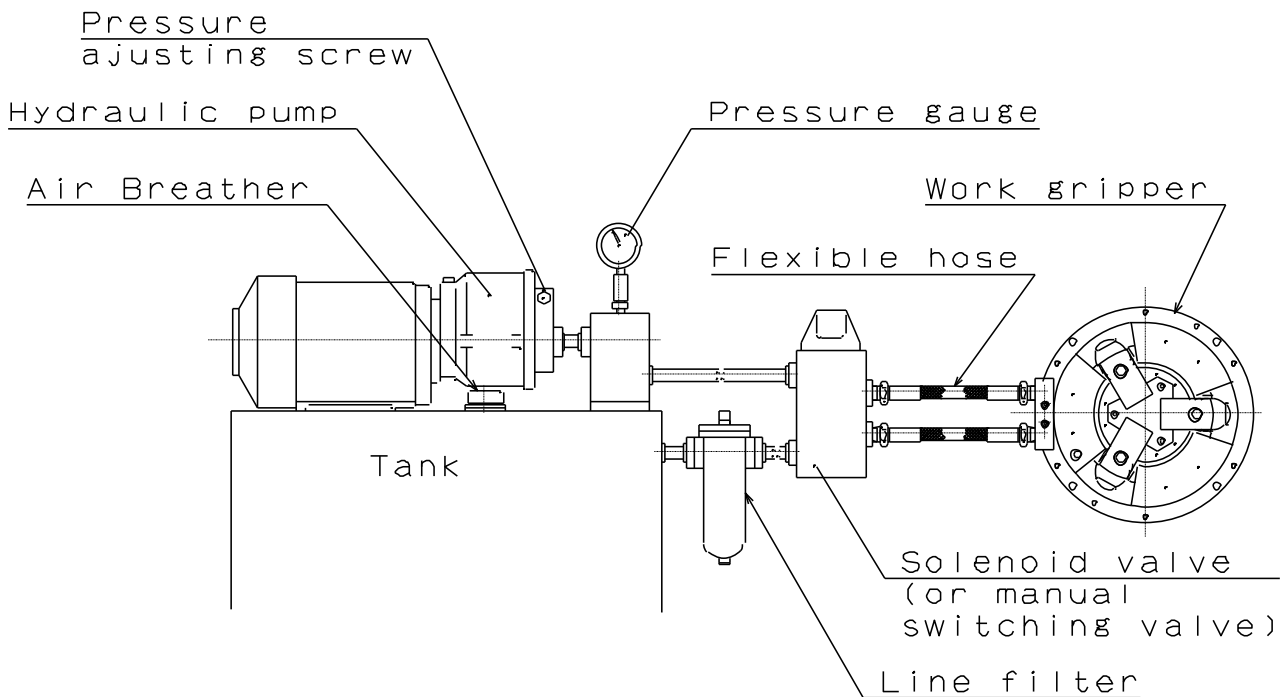


Fig.12

8-1-2. Piping

- Attach the manual switching valve at a position where it is easy to operate for the attaching equipment.
- Install the hydraulic unit at a position where the needle of the pressure gauge is easily read.

DANGER

- When other actuators are operated by the same hydraulic pressure source as the work gripper, be sure that a pressure drop of the work gripper does not occur during use. A hydraulic pressure drop leads to a drop in the gripping force which could allow the work to fly out.

WARNING

- Install after removing the dust inside the pipe completely.
- During the piping, remove dust completely in the piping. Add a filter of 20 μ m or less in the pressure supply line. Presence of dust in the piping causes leakage and then the workpiece to fly out.
- Braided air hose should be used between the switching valve and the work gripper. Use a pipe inside diameter as large as possible and keep the piping length as short as possible.

NOTICE

- Especially, when a large sized hydraulic unit is used, excessive surge pressure is generated and the gripping force becomes large, therefore, it may result in breakage of the chuck or the lowering of endurance. Restrain the surge pressure by adopting a throttle valve, etc.

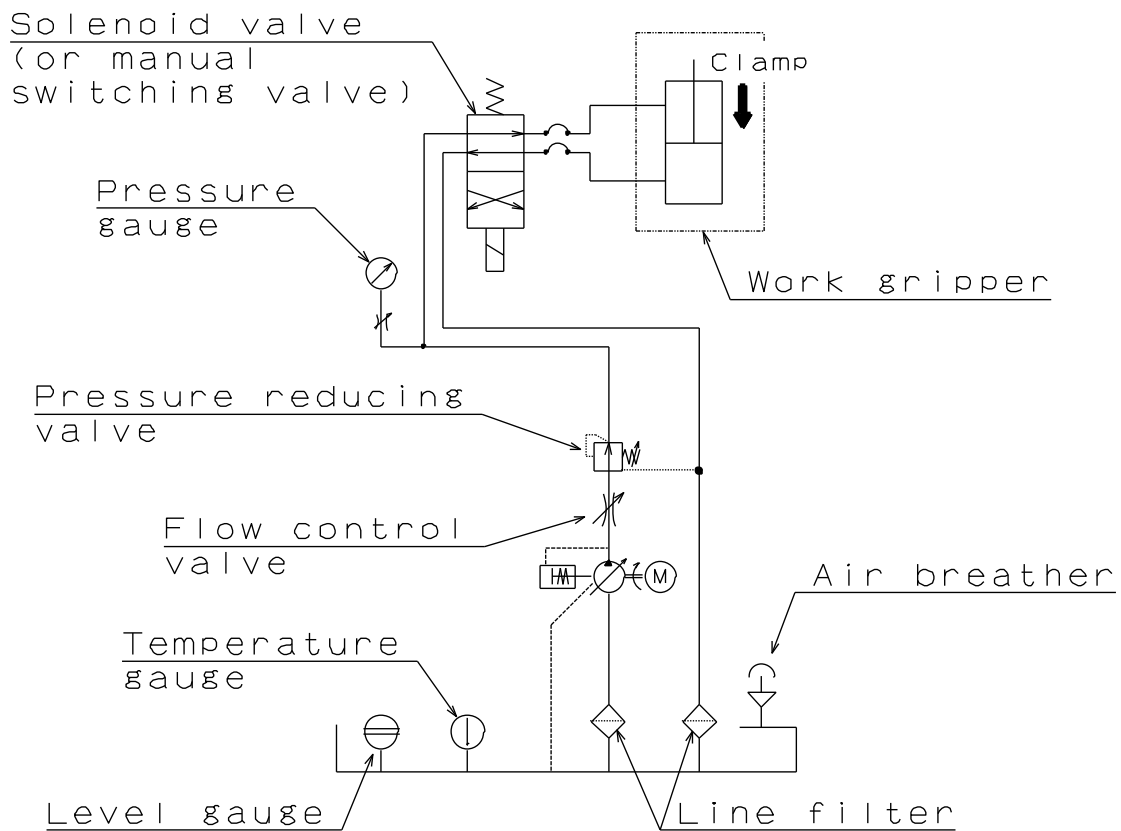


Fig.13

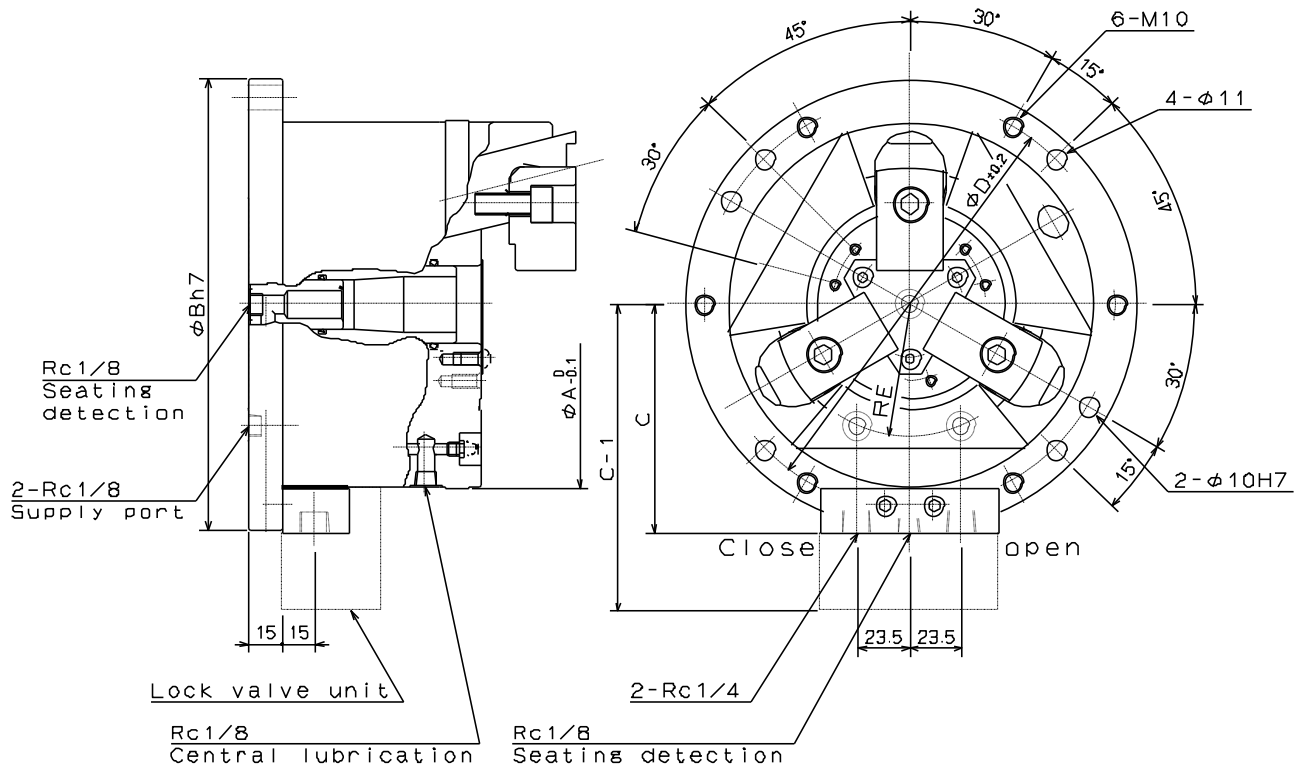


Fig.14

Table 10

Dimension	PLS04	PLS06	PLS08
ϕA	110.1	165.1	210.1
ϕB	148	203	248
C	75.5	103	125.5
C-1	110.5	138	160.5
ϕD	130	185	230
RE	34	60	80

* C-1 show when lock valve unit is installed

9. Trial Operation

Thoroughly read the “Important Safety Precautions” on and after page 11 in this manual before trial operation.

Air pressure

1. Supply grease, following the “6-2.Grease lubrication” on and after page 27 in this manual.
2. Supply turbine oil of additive-free of Class 1 (Viscosity ISO: VG32 or the equivalent) up to the upper extreme end of the indication table of the lubricator of the air control unit.
3. Turn the air pressure adjusting handle and set it to the 0.20-0.25 MPa. Then, make inching of the switching valve, in order to check that the switching valve can operate normally.
4. Turn the needle on the upper part of the lubricator to adjust the drop the site dome. The proper number of drops is 2 or 3 drops per a clamp.
5. Increase the air pressure up to 0.5 MPa, and check to see if air dose not leak and if there is nothing abnormal.

Oil pressure

1. Supply grease, following the “6-2.Grease lubrication” on and after page 27 in this manual.
2. Turn the oil pressure adjusting handle and set it to the 0.4-0.5 MPa. Then, make inching of the switching valve, in order to check that the switching valve can operate normally.
3. Increase the oil pressure up to 1.3 MPa, and check to see if air dose not leak and if there is nothing abnormal.

10. Other information

10-1. About standards and orders

This product is based on the following standards or orders.

- Machinery directive:2006/42/EC Annex I
- EN ISO 12100:2010
- EN1550:1997+A1:2008

10-2. Information about markings of product

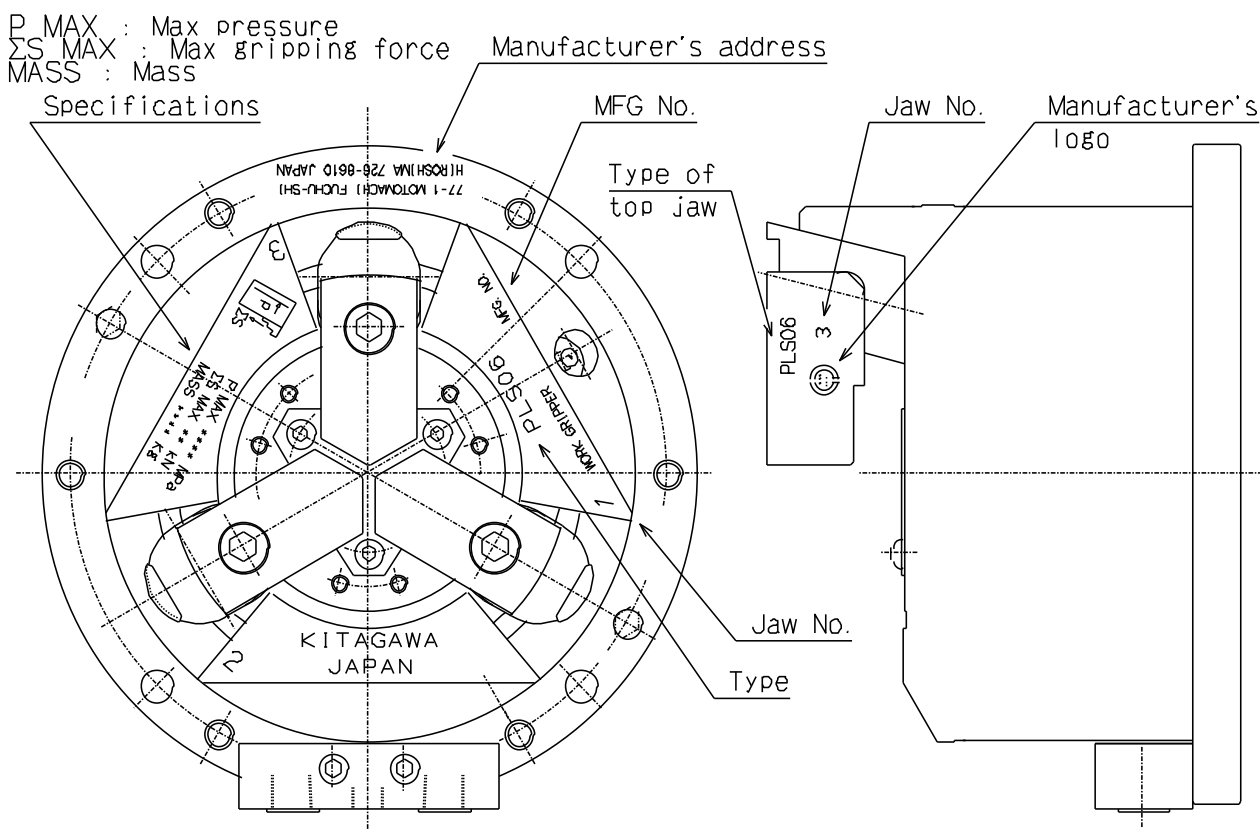


Fig.15

10-3. About disposal

Ultimate disposal of this product should be handled according to all national laws and regulations.

DECLARATION OF INCORPORATION
of partly completed machinery
Copy of original

We hereby declare that the following our product conform with the essential health and safety requirements of the EC Machinery Directive so that the product is to be incorporated into end-machinery. The product must not be put into service until end-machinery has been declared in conformity with the provisions of the EC Machinery Directive 2006/42/EC Annex II part 1.A.

We also declare that the specific technical documentation for this partly completed machinery was drawn up according to the EC Machinery Directive 2006/42/EC Annex VII part B.

Product : Work gripper

Model : PLS series
(Models PLS04,
PLS06, PLS08)

Serial number : See original declaration

Manufacturer : Kitagawa Corporation
77-1, Motomachi, Fuchu-shi,
Hiroshima 726-8610, Japan

Authorized compiler : Peter Soetebier / Prokurist
in the community Kitagawa Europe GmbH
Borsigstr.3 D-40880 Ratingen, GERMANY

The essential health and safety requirements in accordance with the EC Machinery Directive 2006/42/EC Annex I were applied and fulfilled:
1.1.2, 1.1.3, 1.1.5, 1.1.6, 1.3.1, 1.3.2, 1.3.4, 1.5.4, 1.5.8, 1.5.9, 1.5.13, 1.6.1, 1.7.1, 1.7.2, 1.7.3, 1.7.4, 1.7.4.1, 1.7.4.2

The following harmonized standards were applied:
EN ISO 12100:2010, EN 1550:1997+A1: 2008

Signature : See original declaration

Place / Date : See original declaration

Name / Title : Tomonari Hiromoto / Manager, Technical section 1
Technical department
Kitagawa Global hand Company

Being the responsible person appointed and employed the manufacturer.

UK DECLARATION OF INCORPORATION
of partly completed machinery
Copy of original

We hereby declare that the following our product conform with the essential health and safety requirements of the Supply of Machinery (Safety) Regulations 2008 so that the product is to be incorporated into end-machinery. The product must not be put into service until end-machinery has been declared in conformity with the provisions of the Supply of Machinery (Safety) Regulations 2008 Annex II part 1.A.

We also declare that the specific technical documentation for this partly completed machinery was drawn up according to the Supply of Machinery (Safety) Regulations 2008 Annex VII part B.

Product : Work gripper

Model : PLS series
(Models PLS04,
PLS06, PLS08)

Serial number : See original declaration

Manufacturer : Kitagawa Corporation
77-1, Motomachi, Fuchu-shi,
Hiroshima 726-8610, Japan

Authorized complier : Mark Jones / Financial Director
in the community UNIT 1 THE HEADLANS, DOWNTON,
SALISBURY, WILTSHIRE, SP5 3JJ, UNITED
KINGDOM

The essential health and safety requirements in accordance with the Supply of Machinery (Safety) Regulations 2008 Annex I were applied and fulfilled:
1.1.2, 1.1.3, 1.1.5, 1.1.6, 1.3.1, 1.3.2, 1.3.4, 1.5.4, 1.5.8, 1.5.9, 1.5.13, 1.6.1, 1.7.1,
1.7.2, 1.7.3, 1.7.4, 1.7.4.1, 1.7.4.2

The following harmonized standards were applied:
EN ISO 12100:2010, EN 1550:1997+A1: 2008

Signature : See original declaration

Place / Date : See original declaration

Name / Title : Tomonari Hiromoto / Manager, Technical section 1
Technical department
Kitagawa Global hand Company

Being the responsible person appointed and employed the manufacturer.

Kitagawa Corporation Kitagawa Global hand Company

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